

## GIET UNIVERSITY, GUNUPUR - 765022 B. Tech (Sixth Semester Regular) Examinations, May - 2024

21BELPC36003 - Electrical Drives

(EE)

Reg.

No

8

CO1

K2

	(LL)				
Ti		Maximun	n: 70 M	arks	
(The figures in the right-hand margin indicate marks) PART – A (2 x 5 = 10 Mark					
Q.1. Answer <i>ALL</i> questions		X	CO #	Blooms	
a. N	Mention some of the drawback of conventional Ward-Leonard scheme.		CO3	K2	
b. I	Determine rated current of 5MW, 10KV, 50hz synchronous machine operation	ng with	CO4	K3	
e	efficiency of 0.96 & power factor of 0.9.				
c. I	Draw the speed-torque characteristics of DC series motor.		CO2	K3	
d. I	Describe role of microprocessor for speed control of DC motor		CO5	K2	
e. V	Write different stages and drives required for Paper mills.		CO6	K3	
PART – B (15 x 4			= 60 Marks)		
Answer ALL questions Marks		Marks	CO #	Blooms Level	
2. a.	<ul> <li>A constant speed drive has the following duty cycle.</li> <li>i) Load rising from 0 to 400KW; in 5 minutes.</li> <li>ii) Uniform load of 500KW; 5 minutes.</li> <li>iii) Regenerative power of 400KW returned to supply; 4 minutes.</li> <li>iv) Remains Idle for; 2 minutes.</li> <li>Estimate power rating of the motor. Assume losses to be proportional to power.</li> </ul>	8	CO3	K3	
b.	State and explain the various classes of motor duty.	7	CO1	K2	
c.	(OR) Discuss the Ward-Leonard speed control system with a neat circuit diagram.	8	CO4	K2	
d.	Also mention its advantages and disadvantages. Explain VVVF control of 3-phase induction motor.	7	CO5	K3	
3.a.	Draw the block diagram and explain the basic elements of an electric drive	8	CO1	K2	
b.	system. A 3-phase, 4 pole, 415V, 50Hz IM has a star connected stator. The rotor impedance at standstill is $(0.1+J0.9) \Omega$ . The stator to rotor turns ratio is 1.75 Calculate external resistances per phase required in the rotor to limit starting rotor current to 60A.	7	CO3	K3	
	(OR)				
c.	Explain the concept of open loop V $F$ control of synchronous motor.	8	CO4	K3	
d.	Electrical drives are influenced by a number of factors. What are they?	7	CO1	K3	
		0	CO1	K)	

4.a. Explain the various kind of load torques.

b.	Describe the phasor diagram of a synchronous motor working at various rotor excitation levels with a constant load torque. (OR)	7	CO5	K3
c.	A 220V compensated shunt motor drives a 700N-m torque load when running at 1200rpm. The combined armature compensating winding and interlope resistance $0.008\Omega$ and shunt resistance is 55 $\Omega$ . The motor efficiency is 90%. Calculate the value of dynamic braking resistance that will capable of 375Nm torque at 1050rpm. The friction and windage losses may be assumed to remains constant at both speeds.	8	CO2	K3
d.	Define Active load torque and Passive Load Torque. Explain the various components of load torques?	7	CO1	K2
5.a.	How the speed control of the dc drive is achieved using fully controlled rectifier?	8	CO4	K3
b.	Write short notes on drives used in paper mills.	7	CO6	K2
	(OR)			
c.	Draw a typical temperature rise –time curve and derive equation for temperature rise in an electric drive	8	CO2	K3
d.	Describe how microprocessor-based electrical drives operate.	7	CO6	K2

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