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Reg. No



Time 3 hrs

GIET UNIVERSITY, GUNUPUR – 765022

B. Tech (Seventh Semester – Regular) Examinations, November – 2022

BPEAG7021 – Mechatronics

(AGE)

Time: 3 hrs Ma					Maximum: 70	Iaximum: 70 Marks	
		Answ	er ALL Qu	uestions			
		The figures in the ri Aultiple Choice Questions)	ght hand n	nargin indicate marks.			
PA	$(1 \times 10 = 10 \text{ N})$	x 10 = 10 Marks)					
Q.1. Answer ALL questions					[CO#]	[PO#]	
a.						PO1	
	(i)	Decrease	(ii)	Increase			
	(iii)	Be unaffected	(iv)	Any of the above			
b.	A transdue	cer is basically a device which convert	S		CO1	PO1	
	(i)	Mechanical energy into electrical	(ii)	Energy or information from or form to another	ne		
	(iii)	Mechanical displacement into electrical	(iv)	None of these			
c.	Which typ	e of coil is a solenoid?			CO1	PO1	
	(i) E	lectromagnetic	(ii) E	Electrical			
	(iii) M	Iechanical	(iv) C	Chemical			
d.	Filters that	ilters that transmit all frequencies below a defined cut-off frequency are known as			CO2	PO1	
	(i)	Low-pass filters	(ii)	High-pass filters			
	(iii)	Band-pass filters	(iv)	Any of these			
e.	Hydraulic is equivalent of a spring in mechanical systems.			CO3	PO1		
	(i)	Resistance	(ii)	Permittivity			
	(iii)	Inertance	(iv)	None of these			
f.	Rotary mo	otion in a hydraulic power unit is achieved by using			CO3	PO1	
	(i)	Hydraulic cylinder	(ii)	Pneumatic cylinder			
	(iii)	Both (i) and (ii)	(iv)	None the above			
g.	The PLC i	s used in			CO3	PO1	
	(i)	machine tools	(ii)	automated assembly equipme	nt		
	(iii)	mounding and extrusion machines	(iv)	All of the above			
h.	Which among the following applications are not microcontroller based?			CO3	PO1		
	(i)	Computer system	(ii)	Washing machines			
	(iii)	MP3 players	(iv)	Telephones			
i.	Which of	Which of the following sensor work based on radio detection and ranging ?				PO1	
	(i)	Sonar	(ii)	Radar			
	(iii)	Intertial	(iv)	Biosensor			
j.	In which of the following operations continuous path system is used					PO1	
	(v)	Pick and place	(vi)	Load and unloading			
	(vii)	Continuous welding	(viii)	All the above			

PA	RT – B: (Short Answer Questions) (2 x 10 = 20 Marks)		
Q.2.	Answer ALL questions		[CO#]	[PO#]
a.			CO1	PO1
b.	What is static characteristics of instruments?		CO1	PO1
c.	Mention the examples of automatic system?		CO2	PO1
d.	Enumerate the elements of a control system?		CO3	PO1
e.	State the purpose of using potentiometer in displacement sensor?		CO2 PO1	
f.	List out different control valves?	CO3 PO1		
g.	What is ALU? State its function.		CO3	PO1
h.	Highlight the important role of control unit.		CO3	PO1
i.	i. What are the terms that define the performance of the transducers?		CO4	PO1
j.	Write the advantages of robot.		CO4	PO1
PAF	(10 x 4 =	10 x 4 = 40 Marks)		
Ansv	wer ALL questions	Marks	[CO#]	[PO#]
3. a	. Explain the importance of mechatronics with few examples.	5	CO1	PO1
b	. Classify various sensors and briefly explain their applications.	5	CO2	PO1
	(OR)			
C	. Write down the advantages and disadvantages of mechatronics?	5	CO1	PO1
d	. Explain flow transducer and it's importance.	5	CO3	PO1
4. a	. Explain the system modelling and control with suitable example.	5	CO3	PO2
b	Make a short note for the analysis of measurement system as the mechatronics system with example.	5 5	CO3	PO2
	(OR)			
C	Explain the hydraulic mechanical system with suitable example and figure.	10	CO3	PO2
5. a	. Explain the role of computer and interfacings for the system application.	7	CO2	PO2
1	b Define PLC and it's importance.	3	CO3	PO2
	(OR)			
C	e. Explain the modelling and simulation of a dynamic system with suitable diagram.	e 10	CO3	PO2
6. a	. Explain the degree of freedom for the robot and its importance.	5	CO4	PO1
b	Differentiate between Cartesian robot and spherical robot with suitable diagram.	5	CO4	PO1
	(OR)			
C	. List out various applications of robot.	5	CO4	PO1
d	. Explain the working principle of robot used in welding process.	5	CO4	PO1

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