

M. Tech (Structural Engg.)

MSEPC 1030 - Matrix Method of Analysis of structure

Answer key.

PART. A.

a. Degree of redundancy = 1

b. Kinematic indeterminacy = 2.

c. It helps us to represent forces and displacements at the element level, corresponding to every node in the overall structure, there will be as many sets of local co-ordinates as there are elements joining at the node under consideration.

d. ~~The~~ matrix which transforms any desired information of the structure to its corresponding element information or vice versa is termed as transformation matrix.

e. $f = \frac{L}{AE}$

f. The element stiffness matrix is the inverse of element flexibility matrix and vice-versa.

ie $k = \frac{1}{f}$ or $R = \frac{1}{f}$

g. The stiffness co-efficient K_{ij} is defined as the force developed at joint 'i' due to a unit displacement at joint 'j', while other joints are assumed to be fixed.

h. Displacements are considered as the unknown quantities

i. All the steps in the stiffness method can be executed by a computer more conveniently. As the solution procedure is unique. It does not depend on the user for the choice of the primary structure. Hence, programming is simplified. The structure stiffness matrix for a stable linear structure is invariably a well-conditioned matrix, thereby facilitating accurate solution of the response.

j. $\dot{x} = (bm + tr) - b_j$

External indeterminacy = 18

Internal indeterminacy = 6

PART - B

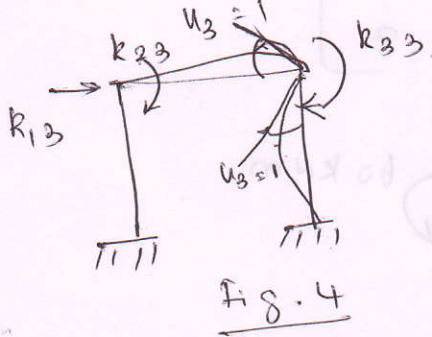
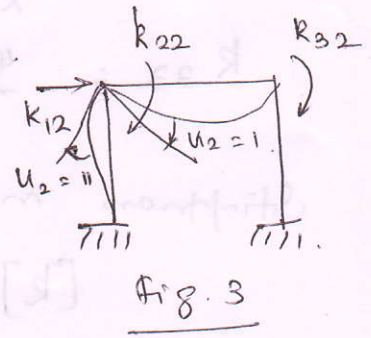
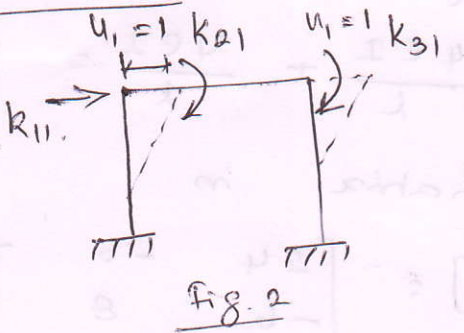
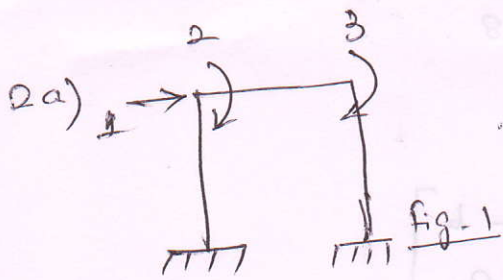


Fig. 1

Stiffness coord.

matrix to be developed for the 1, 2 and 3.

To generate 1st column of the stiffness matrix, apply unit displacement @ coordinate 1 as shown in Fig. 2.

$$R_{11} = \frac{12EI}{l^3} + \frac{12EI}{l^3} = 24.$$

$$R_{21} = \frac{-6EI}{l^2} = -6 ; \quad R_{31} = \frac{-6EI}{l^2} = -6.$$

To generate 2nd column, apply unit displacement at 2.

$$R_{12} = \frac{-6EI}{l^2} = -6 ; \quad R_{22} = \frac{4EI}{l^2} + \frac{4EI}{l} = 8$$

$$R_{32} = \frac{2EI}{l} = 2.$$

To generate 3rd column, apply unit displacement at 3

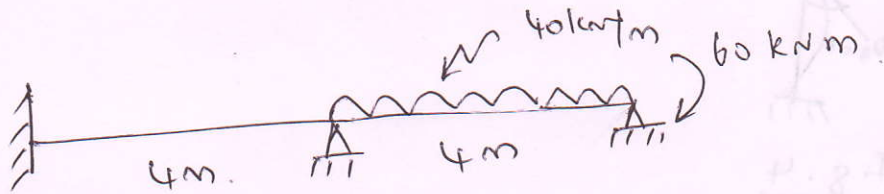
$$K_{13} = \frac{-6EI}{l^2} = -6; \quad K_{23} = \frac{2EI}{l} = 2;$$

$$K_{33} = \frac{4EI}{l} + \frac{4EI}{l} = 8.$$

Stiffness matrix is

$$[K] = \begin{bmatrix} 24 & -6 & -6 \\ -6 & 8 & 2 \\ -6 & 2 & 8 \end{bmatrix}$$

3A.



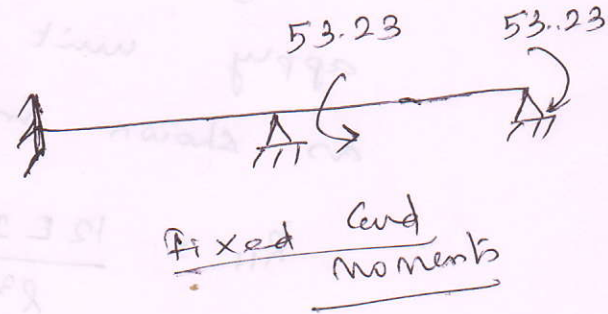
(1) Fixed end moments.

$$M_{FA} = M_{FB} = 0$$

$$M_{FC} = M_{CB} = -\frac{40 \times 4^2}{12} = -53.23 \text{ kNm}$$

$$= +53.23 \text{ kNm}$$

$$[P^0] = \begin{Bmatrix} 0 \\ 0 \\ -53.23 \\ +53.23 \end{Bmatrix} \text{ kNm.}$$

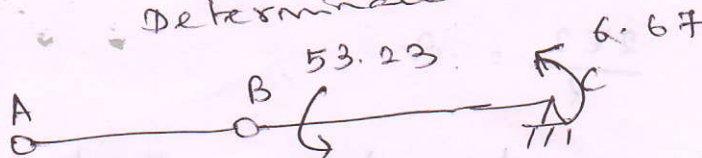


(2) Static indeterminacy = 2

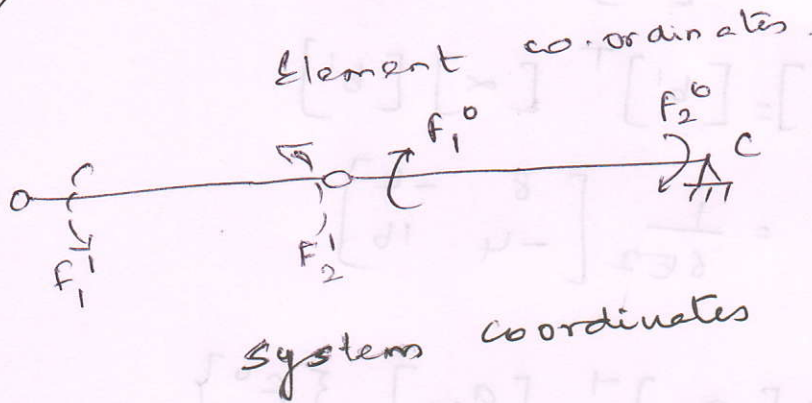
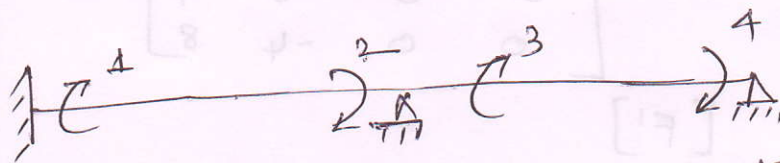
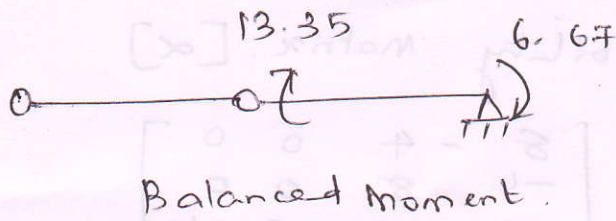
Introduce hinges at A and B.



Determinate structure.



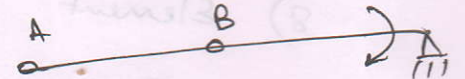
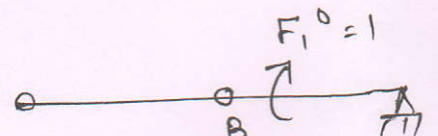
Unbalanced moment.



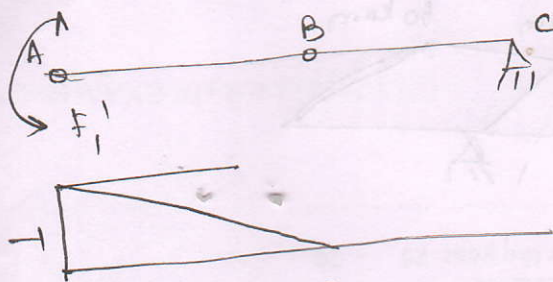
$$[F^0] = \begin{bmatrix} 53.33 \\ 6.67 \end{bmatrix}$$

3) Apply unit forces (moment) F_1^0 & F_2^0 @ 3rd & 4th co-ordinates separately

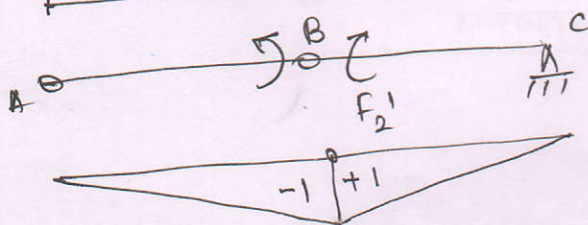
$$[b^0] = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$



4) Apply unit redundant forces F_1^1 & F_2^1 to generate 1st & 2nd columns of $[b^1]$



$$[b^1] = \begin{bmatrix} -1 & 0 \\ 0 & -1 \\ 0 & -1 \\ 0 & 0 \end{bmatrix}$$



5) Element flexibility matrix $[\alpha]$

$$[\alpha] = \frac{1}{6EI} \begin{bmatrix} 8 & -4 & 0 & 0 \\ -4 & 8 & 0 & 0 \\ 0 & 0 & 8 & 4 \\ 0 & 0 & -4 & 8 \end{bmatrix}$$

6) To generate $[F']$

$$[a_{11}] = [b']^T [\alpha] [b']$$

$$= \frac{1}{6EI} \begin{bmatrix} 8 & -4 \\ -4 & 16 \end{bmatrix}$$

$$7) \{F'\} = -[a_{11}]^{-1} [a_{10}] \{F^0\}$$

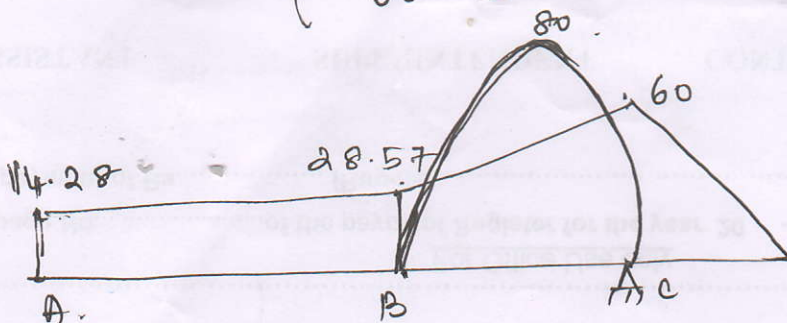
$$= -[a_{11}]^{-1} [b']^T [\alpha] [b^0] \{F^0\}$$

$$= \begin{Bmatrix} 14.28 \\ -28.57 \end{Bmatrix}$$

8) Element forces $\{P\}$

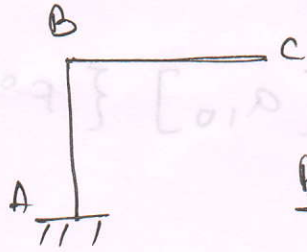
$$\{P\} = [b^0] \{F^0\} + [b'] \{F'\} + \{P^0\}$$

$$= \begin{Bmatrix} 14.28 \\ 28.57 \\ -28.57 \\ 60 \end{Bmatrix} \text{ kNm}$$



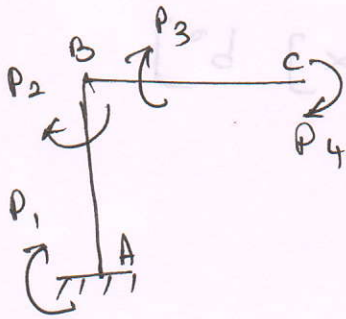
BMD

4a) Static indeterminacy = 1

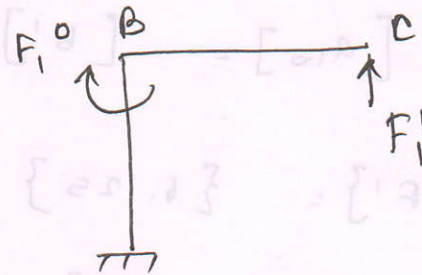


Primary structure

Consider ~~the~~ reaction at C as redundant force.

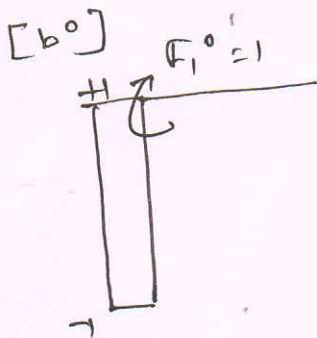


Element co. ord



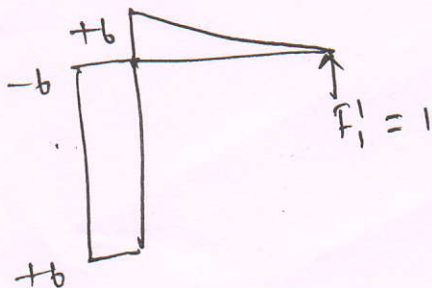
System co. ord

Apply unit external force F_1^0 at B to generate



$$[b^0] = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Apply unit redundant force F_1^1 to generate $[b^1]$



$$[b^1] = \begin{bmatrix} b \\ -b \\ b \\ 0 \end{bmatrix}$$

Element flexibility matrix $[\alpha]$

$$[\alpha]_E = \frac{6}{6EI} \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

to generate = $\{F'\}$

$$\{F'\} = - [a_{11}]^{-1} [a_{10}] \{F^0\}$$

Where

$$[a_{11}] = [b']^T [\alpha] [b']$$

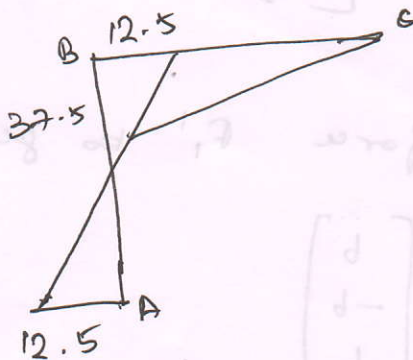
$$[a_{10}] = [b']^T [\alpha] b^0$$

$$\{F'\} = \{6.25\}$$

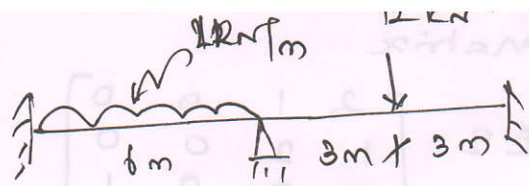
Element forces $\{P\}$

$$\{P\} = [b^0] \{F^0\} + [b'] \{F'\}$$

$$= \begin{Bmatrix} -12.5 \\ 12.5 \\ 37.5 \\ 0 \end{Bmatrix} \text{ KN.m.}$$



5a)



Fixed end moments, $[P^0]$

$$M_{FAB} = \frac{-2 \times b^2}{12} = -6 \text{ kNm}$$

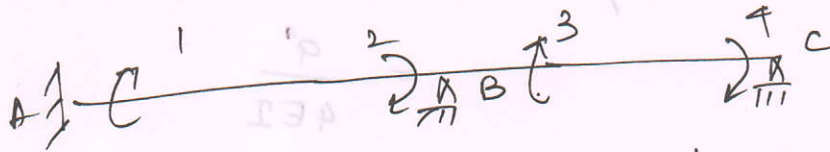
$$M_{FBA} = +6 \text{ kNm}$$

$$M_{FBC} = \frac{-12 \times b}{8} = -9 \text{ kNm}$$

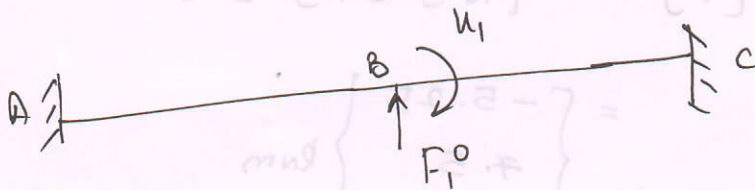
$$M_{FCB} = +9 \text{ kNm}$$

$$[P^0] = \begin{Bmatrix} -6 \\ 6 \\ -9 \\ 9 \end{Bmatrix}$$

Kinematic indeterminacy = 1

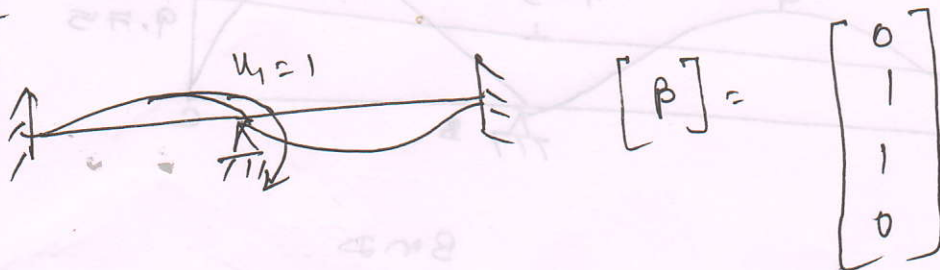


Element coord



System coord

Apply unit displacement to generate $[P]$



Element stiffness matrix

$$[k] = EI \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

System stiffness matrix

$$[K] = [\beta]^T [k] [\beta]$$

$$= \frac{4EI}{3}$$

$$[K]^{-1} = \frac{3}{4EI}$$

To generate $\{F\} = \{P\}^f - [\beta]^T \{P^o\}$

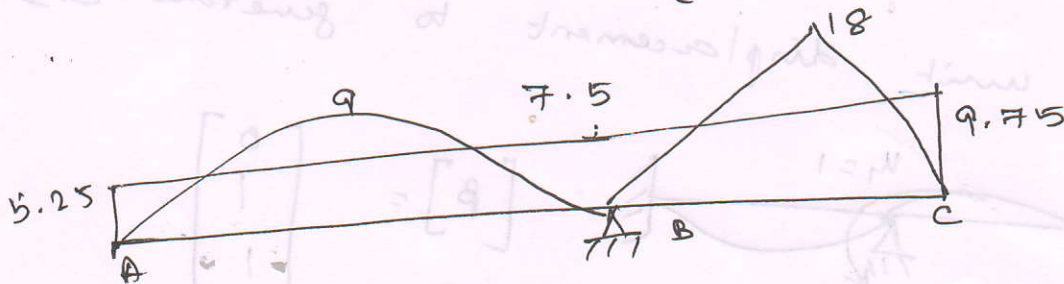
$$= \{3\}$$

System deformation, $\{u\} = [K]^{-1} \{F\}$

$$= \frac{9}{4EI}$$

Element forces, $\{P\} = [k] [\beta] \{u\} + \{P^o\}$

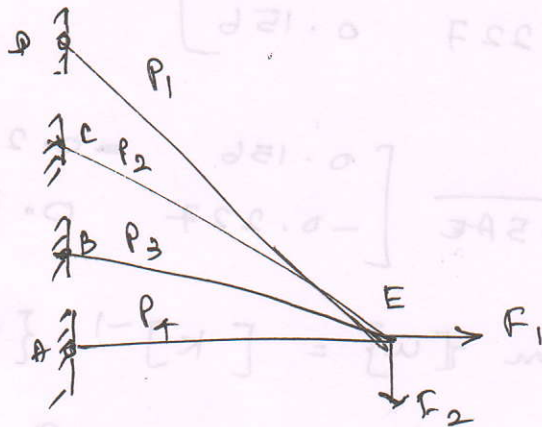
$$= \begin{Bmatrix} -5.25 \\ 7.5 \\ -7.5 \\ 9.75 \end{Bmatrix} \text{ kNm}$$



BMD

6a) degrees of freedom = 2.

Root ~~is~~ ~~can~~ ..



System co-ord & Element co-ord.

External load vector, $\{F\} = \begin{Bmatrix} 200 \\ 100 \end{Bmatrix}$

To generate force transformation matrix $[E]$

Consider equilibrium of joint E

$$F_1 = P_1 \cos 45^\circ + P_2 \cos 33.69^\circ + P_3 \cos 18.43^\circ$$

$$F_2 = P_1 \sin 45^\circ + P_2 \sin 33.69^\circ + P_3 \sin 18.43^\circ$$

$$[E] = [B]^T \begin{bmatrix} 0.707 & 0.707 \\ 0.832 & 0.555 \\ 0.949 & 0.316 \\ 4 & 0 \end{bmatrix}$$

To generate element stiffness matrix $[k]$

$$[k] = AE \begin{bmatrix} 1/6.364 & 0 & 0 & 0 \\ 0 & 1/5.408 & 0 & 0 \\ 0 & 0 & 1/4.743 & 0 \\ 0 & 0 & 0 & 1/4.5 \end{bmatrix}$$

System stiffness matrix $[K] = [B]^T [k] [B]$

$$= AE \begin{bmatrix} 0.618 & 0.227 \\ 0.227 & 0.156 \end{bmatrix}$$

$$[K]^{-1} = \frac{1}{0.045AE} \begin{bmatrix} 0.156 & -0.227 \\ -0.227 & 0.618 \end{bmatrix}$$

System deformation $[u] = [K]^{-1} [F]$

$$= \frac{1}{AE} \begin{bmatrix} 188.89 \\ -635.55 \end{bmatrix}$$

Element forces $[P] = [k] [B] [u]$

$$= \begin{bmatrix} -49.69 \\ -36.22 \\ -4.23 \\ 41.93 \end{bmatrix} \text{ kN}$$

7a) Fixed end moments $[P^0]$

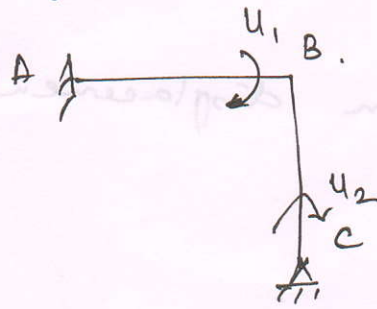
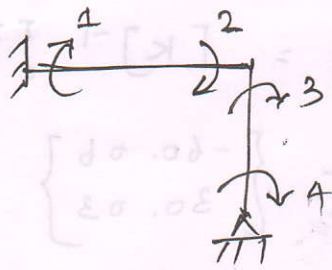
$$M_{FAB} = \frac{-wL^2}{12} = -180 \text{ kNm}$$

$$M_{FBA} = +180 \text{ kNm}$$

$$M_{FBC} = M_{FCB} = 0$$

$$[P^0] = \begin{bmatrix} -180 \\ +180 \\ 0 \\ 0 \end{bmatrix}$$

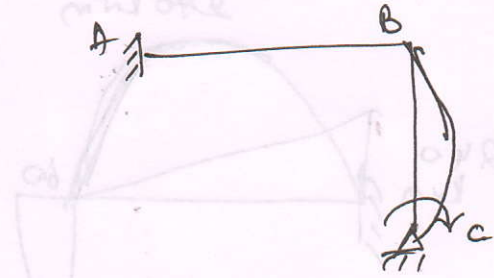
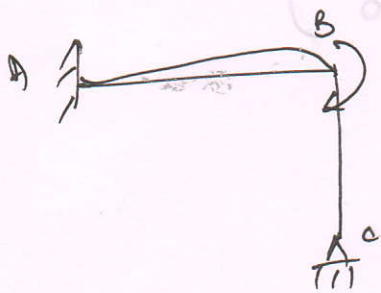
Kinematic indeterminacy = 2



Element w. ord

System w. ord

Apply unit displ. @ 3rd & 4th w. ord.
to generate 1st & 2nd columns of $[B]$.



$$[B] = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Element stiffness matrix, $[k] = EI \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 4/3 & 2/3 \\ 0 & 0 & 2/3 & 4/3 \end{bmatrix}$

System stiffness matrix, $[K] = [B]^T [k] [B]$

$$[K] = EI \begin{bmatrix} 10/3 & 2/3 \\ 2/3 & 4/3 \end{bmatrix}$$

$$[K]^{-1} = \frac{1}{4EI} \begin{bmatrix} 4/3 & -2/3 \\ -2/3 & 10/3 \end{bmatrix}$$

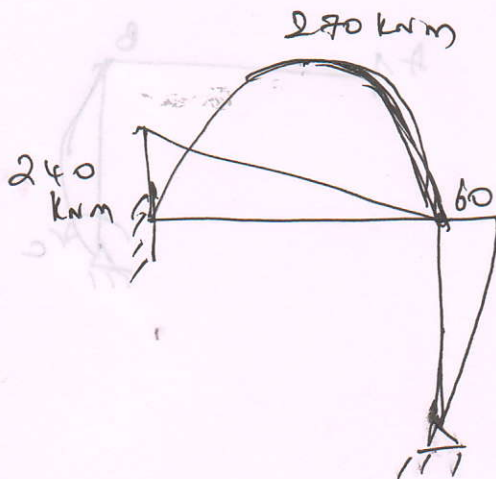
$$\{F\} = \{F\}^f - [B]^T \{P^0\} = \begin{Bmatrix} -180 \\ 0 \end{Bmatrix} \text{ kN}$$

system displacement, $\{u\} = [K]^{-1} \{F\}$

$$= \frac{1}{EI} \begin{Bmatrix} -60.06 \\ 30.03 \end{Bmatrix}$$

Element forces, $\{P\} = [k_r] [B] \{u\} + \{P^0\}$

$$= \begin{Bmatrix} -240 \\ 60 \\ -60 \\ 0 \end{Bmatrix}$$



8. a) Techniques used to reduce memory requirement for storing the stiffness matrix

(1) Use of symmetry & banded nature

(2) Partitioning of matrix

(3) skyline storage.

Explanation on the above types.