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Total number of printed pages – 2

B. Tech
PEEE 5407

Seventh Semester (Special) Examination – 2013

INDUSTRIAL AUTOMATION AND CONTROL

BRANCH : AEIE, EC, EEE, ETC, IEE

QUESTION CODE : 464

Full Marks – 70

Time : 3 Hours

Answer Question No. 1 which is compulsory and any **five** from the rest.

The figures in the right-hand margin indicate marks.

1. Answer the following questions : 2×10
- How multivariable control is more suitable in process control operation ?
 - Represent the basic method of tuning necessary for PID Controller during operation.
 - What are the algorithm required to programming three mode of digital PID Controller ?
 - What is the disadvantages of feed forward control ?
 - Explain the function of selective control.
 - Basically how many type of selective control are available in multi-loop control system ?
 - Distinguish the advantages and disadvantages of pneumatic actuator.
 - What is the difference between relay diagram and ladder diagram ?
 - Explain the communication method in DCS.
 - Represent multi-tasking associated with real time operating system in process control.
2. (a) Compare the P, PI, PD Controller in terms of their transient and steady state performance. 5
- (b) Represent the presence of off-set in simple "P" mode operation. 5

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3. (a) Describe any one algorithm use for Digital PID Controller programming. 5
 (b) Explain in details about the functioning of open loop response curve in PID Control tuning. 5
4. (a) What do you mean by the phenomena of shrink and swell in boiler dram level control? 4
 (b) Explain with suitable example of feedback- feed forward control configuration. 6
5. (a) Describe with a sketch the principle of operation of a flapper-nozzle amplifier. 4
 (b) Briefly explain all about electrical actuator necessary in process control and automation. 6
6. (a) With neat sketch explain the architecture and functional requirement of DCS. 4
 (b) Define the following : 6
 (i) task management
 (ii) memory management
 in real time operating system used for process control application.
7. (a) Define the following related to controller : 5
 (i) two position control
 (ii) multi-position control
 (b) Describe distributed vs centralised control 5
8. Write short notes on any **two** of the following : 5×2
 (a) Communication option on DCS
 (b) Real time operation system
 (c) Distributed control system
 (d) Adaptive control.

