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Total number of printed pages – 2

B. Tech
PEEE 5407

Seventh Semester Back Examination – 2014

INDUSTRIAL AUTOMATION AND CONTROL

BRANCH (S) : AEIE, EC, EEE, ETC, IEE

QUESTION CODE : L195

Full Marks – 70

Time : 3 Hours



Answer Question No. 1 which is compulsory and any **five** from the rest.
The figures in the right-hand margin indicate marks.

1. Answer the following questions : 2 × 10
 - (a) Define controlled variable, manipulated variable, and load variable with suitable example.
 - (b) Define resistance and capacitance of a process. What do you mean by dead time in a process ?
 - (c) Define proportional band (PB).
 - (d) State and explain elements of a controller.
 - (e) What do you mean by offset error ? How do you overcome it ?
 - (f) List major functions of an adaptive control process.
 - (g) State the condition to use Split-range control scheme in a process.
 - (h) What is the difference between relay diagram and ladder diagram ?
 - (i) What do you mean by real time programming ?
 - (j) Which is a single mode controller that cannot be used alone and why ?
2.
 - (a) Describe the characteristics of Proportional control, Integral control and Derivative control. Write suitability and limitations of their applications in process control. 5
 - (b) Explain non-interacting position PID algorithm. 5
3. (a) A self-actuating PI controller is used to control the temperature of a process. The following data is known : 100% measurement input = 200 °F deviation in process temperature; 100% controller output = $\frac{3}{4}$ inch valve deviation; PB = 20%; Reset rate = 2 Repeats/min; The process temperature suddenly

P.T.O.

deviates by 2 °F above the set point and remains there. Calculate the total valve deviation after 2 minutes. 5

(b) Draw the block diagram of a cascade control system and describe the function of each unit. Write the characteristics of cascade control. 5

4. (a) Explain the working principle of feed forward control of distillation column. 5

(b) Discuss the auctioneering control of catalytic tubular reactors with highly exothermic reaction. 5

5. (a) Discuss different Pneumatic actuation methods with suitable diagram. 5

(b) Explain the control strategy used in Figure 1 below. 5

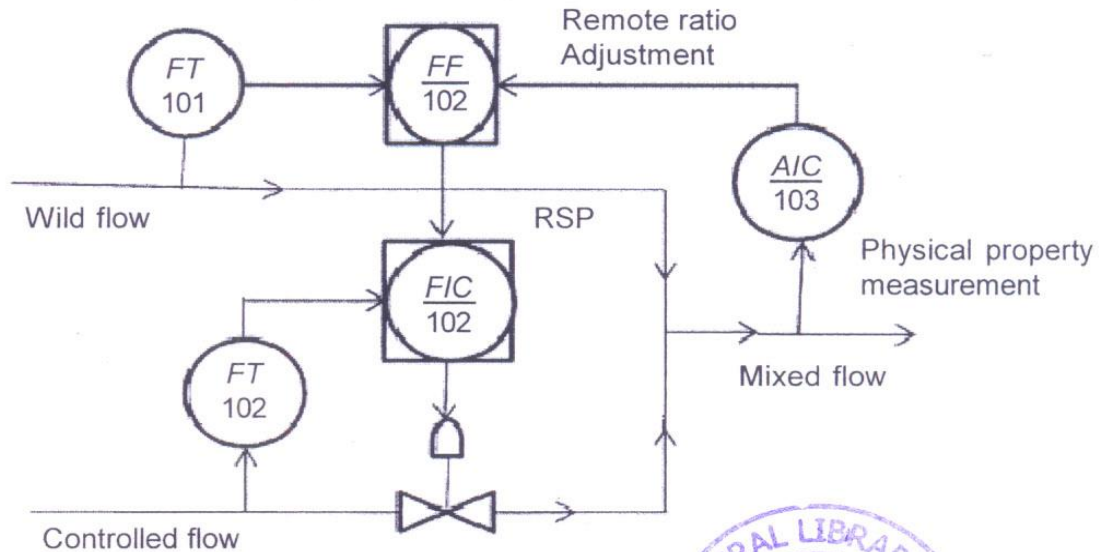


Figure 1

6. (a) Explain the working principle of relay. 5

(b) Three tanks containing oil have to be monitored continuously. Design a warning system to light up whenever two or more tanks are empty. A NO switch at the bottom of each tank gets energized whenever a tank is found empty. 5

7. (a) Draw a hierarchical DCS structure and explain function at each level. 5

(b) Give an example of multi-tasking process. Draw and describe state transition diagram of tasks. 5

8. Write short notes on any **two** of the following : 5 × 2

(a) Feed forward-feedback control configuration

(b) Control Valves

(c) End-point control

(d) Gain scheduling adaptive control.