

GIET UNIVERSITY, GUNUPUR – 765022

6+10

	RD3	L9MSC014	
	Roll No:		
Tota	al Number of Pages: 2 AR-19	M.Sc	
100	M.Sc 1 ST SEMESTER REGULAR EXAMINATIONS, NOV/DEC 2019-20	1,1.50	
	PHPC102-CLASSICAL MECHANICS		
	Time: 3 Hours The figures in the right hand margin indicate marks. Max Marks:	80	
SECTION – A			
Q.:	1 Answer any four of the following $[4\times4=1]$	6]	
а	Explain orthogonal transformations.	4	
b	Show that the kinetic energy of a rigid body is $\frac{1}{2}\vec{L}.\vec{\omega}$, where \vec{L} is the angular	4	
	momentum and $\vec{\omega}$ is the angular velocity of the rigid body.		
С	Show that the shortest curve joining two points is a straight line.	4	
d	Prove that for a conservative system, the Hamiltonian function H represents the total energy of the system.	4	
e	Show that the transformation $P = \frac{1}{2}(p^2 + q^2)$ and $Q = \tan^{-1}\left(\frac{q}{p}\right)$ is canonical.	4	
f	What is Poisson bracket? State its properties.	2+2	
	OR		
2. /	Answer all questions from the following. [2×8=1	.6]	
а	What do you understand by inertia tensor?	2	
b	What is the effect of coriolis force on a particle thrown horizontally at earth's north pole?	2	
С	State Hamilton's principle.	2	
d	Explain the principle of least action.	2	
е	State Poisson's theorem.	2	
f	Define Lagrange bracket.	2	
g	What is meant by integral invariance of Poincare?	2	
h	State Liouville's theorem.	2	
SECTION-B			
3. <i>A</i>	Answer all Questions. [16×4]	_	
а	What are Euler angles? Find out the complete transformation matrix in terms of Euler angles, if a three dimensional coordinate system is transformed to another having same origin.	2+14	
L	OR	0.0	
b	Derive Euler's equations of motion of a rotating rigid body. Then, discuss about the torque free motion of the rigid body.	ŏ +Ծ	
4.		_	
а	What is meant by calculus of variations? Using the calculus of variations, derive Euler- Lagrange equation.	2+14	
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b What is Legendre transformation? Derive Hamilton's equations of motion.



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5.		
а	What are canonical transformations? Find out the generating function of canonical transformations and write the four forms of generating function. OR	6+8+2
b	Explain the harmonic oscillator problem as an example of Hamilton – Jacobi method.	16
6.		
a	Explain normal coordinates and normal modes of small oscillations. OR	16
b	Describe the theory of coupled system of two oscillators and find out the normal mode frequencies.	16