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Total Number of Pages : 02

B.Tech  
PET5I102

5<sup>th</sup> Semester Regular / Back Examination 2019-20

DIGITAL SIGNAL PROCESSING

BRANCH : ECE, ETC

Max Marks : 100

Time : 3 Hours

Q.CODE : HRB168

Answer Question No.1 (Part-1) which is compulsory, any EIGHT from Part-II and any TWO from Part-III.

The figures in the right hand margin indicate marks.

Part- I

Q1 Only Short Answer Type Questions (Answer All-10) (2 x 10)

- Why the ROC of Z-transform cannot contain any pole?
- Why it is not possible to take the DFT of sequence having infinite length?
- What do you mean by 'twiddle factor' of DFT & show how it is cyclic?
- Give the computational efficiency of FFT over DFT.
- What is frequency warping effect?
- Give the various steps involved in the design of IIR filter.
- What are the three quantization errors due to finite word length registers in digital filters?
- List the various features of DSP processors.
- What is the role Barrel shifter in ADSP-21xx?
- What do you mean by symmetric and anti-symmetric FIR filters?

Part- II

Q2 Only Focused-Short Answer Type Questions- (Answer Any Eight out of Twelve) (6 x 8)

- Determine the response of the relaxed system characterized by the impulse response  $h[n] = 0.5^n u[n]$  and input  $x[n] = 2^n u[n]$
- Check whether the given systems are linear, shift variant, causal and stable
  - $y[n] = x[4n+1]$
  - $y[n] = x[n] + nx[n+1]$
- Find the Fourier transform of  $\text{sgn}(n)$  and sketch the spectra.
- With the help of  $N = 8$ , explain radix-2 decimation-in-frequency (DIF) FFT algorithm for computation of DFT. Give the computational efficiency of FFT over DFT.
- Realize the given system in direct form-I  $y[n] = 0.5y[n-1] - 0.25y[n-2] + x[n] + 0.4x[n-1]$ .
- State the desirable properties required to convert an analog filter to a digital IIR filter give methods for the same.
- Explain with a suitable example the steps for design of linear phase filters using hamming window.
- Write short note on Architecture of ADSP series of digital signal processors.

- i) A discrete-time system is defined by the difference equation,  $y[n] = x[n] + x[n - 10]$ . Compute and sketch its magnitude and phase response for frequency 0 to  $2\pi$ . Determine output  $y[n]$  of this system if the input to it is,  $x[n] = \cos(n\pi/10) + 3\sin((n\pi/3) + (\pi/10))$ .
- j) Show why Hilbert Transformer is termed as a 90-degree phase shifter. How can it be used to calculate instantaneous frequency?
- k) Compare Chebyshev and Butterworth filters.
- l) Obtain the coefficients of a linear phase 13 order FIR filter to meet the specifications given below using the window method :
- stopband attenuation = 20 dB  
 Transition width = 0.5KHz  
 Sampling frequency = 8 KHz  
 Passband edge frequency = 1.5 KHz

### Part-III

#### Only Long Answer Type Questions (Answer Any Two out of Four)

- Q3** Two 4-point sequences are defined as  $x[n] = \cos(n\pi/2)$  and  $h[n] = 2^n$  for  $n = 0, 1, 2, 3$ . Calculate 4-point DFTs,  $X(k)$  and  $H(k)$ . Calculate 4-point circular convolution of  $x[n]$  and  $h[n]$  directly. Calculate inverse DFT of the product of  $X(k)$  and  $H(k)$  and compare it with the previous result. **(16)**
- Q4** Find the output response of the discrete time system described by the following difference equation.  $y[n] - 0.75y[n-1] + 0.166y[n-2] = x[n]$  where  $x[n] = (1/5)^n u[n]$  subjected to the initial conditions  $y[-1] = 0$  and  $y[-2] = 1$ . Also find out the step response. **(16)**
- Q5** For the analog transfer function  $F(s) = \frac{2}{(s+1)(s+2)}$ . Determine its digital equivalent using impulse invariance method and bilinear transformation method taking  $T = 1$  sec **(16)**
- Q6** For a real, causal sequence  $x[n]$ , it is given that  $\text{Im}\{X(e^{j\omega})\} = 3\sin\omega + \sin(3\omega)$ . Calculate  $x[n]$  and show if you can get a unique solution of it. If it is additionally mentioned that,  $X(e^{j\omega}) = 3$  at  $\omega = \pi$ , what would be the value of  $x[n]$ ? Hence, calculate  $\text{Re}\{X(e^{j\omega})\}$ . **(16)**