	Registration No: -					
Total Number of Pages:02210		210	210	210	210	B.Tech210
PEE5I103 5th Semester Regular / Back Examination 2019-20 DIGITAL SIGNAL PROCESSING BRANCH: EEE						
Max Marks: 100 Time: 3 Hours 210 210 210 210 210 210 210 210 210 210						
The figures in the right hand margin indicate marks. Part- I						
Q1					e. etc	(02x10)
a) b) c)	How is an LTI system chara Differentiate between zero in State the modulation prope Enumerate those properties	cterized in discrete time nput and zero-state res rty in DTFT.	e domain. ponse of a discrete	e system.	210	210
d) e) f) g) h)	? State the common characte Give the weight updation rul Express and explain the rela Give the difference equation What is the z-transform of the	le for LMS algorithm, ex ationship between Disc n and system function e	xplaining each para rete Fourier Transf expression for an F	form and Fourier T		210
i)	$x(n) = \{1,3,4,7,0,1\}$					
j)	Comment on the shape of ROC for an infinite duration, right-sided signal? Part- II					
Q2 Only Focused-Short Answer Type Questions- (Answer Any Eight out of Twelve) (06x08) Analyze, Justify, Design, Formulate, Calculate, Develop, Illustrate, Explain, Distinguish, Differences &						
a)	210 210 Determine the particular sol	ution of the difference e		210	210	210
b)	When the forcing function is The impulse response of a	Linear Time Invariant s	system is $h(n) =$	$\{1,3,-1,2\}$ and	is excited by an	
c)	input $x(n) = \{1, 4, 3, -11\}$ Define what are poles and a same number of poles and a	zeros of a z-transform	X(z). Explain with	an example that the	nere are exactly	210
d)	Compute the convolution of	the following signals by	y means of z-trans	•		
		• '	$\left(\frac{7}{3}\right)^n, n \ge 0$ $\left(\frac{1}{2}\right)^n, n < 0$			
	210 210	$x_{2}^{10}(n) =$	$\left(\frac{1}{2}\right)^n u(n)$	210	210	210
e)	What is the significance of using time domain formula:			ılar convolution of	the sequences	
		± ' '	{1,2,3,1} {4,3,2,2}			

