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Total Number of Pages: 2

**B.TECH**  
**FEEE6301**

**6<sup>th</sup> Semester Regular / Back Examination 2015-16**  
**INDUSTRIAL PROCESS CONTROL AND DYNAMICS**  
**BRANCH(S): EEE, ELECTRICAL, METTA, MM**

**Time: 3 Hours**

**Max Marks: 70**

**Q.CODE:W585**

**Answer Question No.1 which is compulsory and any five from the rest.**  
**The figures in the right hand margin indicate marks.**

**Q1** Answer the following questions: **(2 x 10)**

- What is need for linearization of signals?
- Draw the circuit of an integrator for analog signal conditioning.
- State the parameter considered for analysis of OpAmp with non-ideal response.
- Draw the circuit diagram of a differential amplifier.
- What is Pyrometry?
- What is meant by tuning a controller?
- How capacitive sensor used for measurement of displacement.
- State the advantage and disadvantage of feed-forward control scheme.
- What is offset error in proportional controller?
- Why derivative controller cannot be used alone?

**Q2 a)** Explain the operation of voltage to current converter with suitable diagram. Derive the relation between maximum load resistance and maximum current. **(5)**

**b)** Draw circuit diagram and explain application of instrumentation amplifier in signal conditioning circuits. **(5)**

**Q3 a)** Explain the principle of operation of a parallel-feedback A/D converter. **(5)**

**b)** State the characteristics of DAC. **(5)**

**Q4** For an error signal where,  $e_p = t$  for time,  $t = 1$  to  $2$  sec,  $e_p = 1$  for  $t = 1$  to  $3$  sec and  $e_p = 0$  for  $t > 3$  sec. Plot a graph of a PID controller output as a function of time for given  $K_p = 2$ ,  $K_i = 0.5s^{-1}$ ,  $K_d = 0.5s$  and  $P(0) = 50\%$ . **(10)**

**Q5 a)** Draw the PLC block diagram and explain each block. **(5)**

**b)** Explain the PLC scan cycle. What is scan time? **(5)**

**Q6 a)** With a suitable example describe the working of a self-regulated process and why is it called self regulated? **(5)**

**b)** Describe characteristic of Proportional-Integral Controller. **(5)**

**Q7 a)** Explain various schemes of ratio controller. **(5)**

**b)** Distinguish between feed forward and feedback control scheme. **(5)**

**Q8** Write short notes on any two of the following **(5 x 2)**

**a)** Flapper-Nozzle system

**b)** Cascade control of Jacketed CSTR

**c)** Auctioneering control of Catalytic tubular reactor

**d)** Thermocouple