

Registration No. :

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Total number of printed pages – 3

B. Tech
PCBM 4302

Fifth Semester (Special) Examination – 2013

SIGNALS AND SYSTEMS

BRANCH : AEIE, BIOMED, CSE, EC, ETC, IEE, IT

QUESTION CODE : D 315

Full Marks – 70

Time : 3 Hours

Answer Question No. 1 which is compulsory and any **five** from the rest.

The figures in the right-hand margin indicate marks.

1. Answer the following questions :

2×10

- Define convolution of two signals. Write the expression for convolution expression of two discrete signals.
- What is causal signal and causal system ?
- Find the circular convolution of the signal $X(n)=\{1,-i, 1,-1\}$ and $Y(n) = \{1,0 1,i\}$
- What is BIBO stability and write the condition for LTI system ?
- State and derive the time reversal property of z-transform.
- State the interconnection of discrete time system.
- What is twiddle factor ?
- State initial value theorem and final value theorem.
- State complex conjugate property of DFT.
- $y(n)=-n$ is a causal signal or not ? Justify.

P.T.O.

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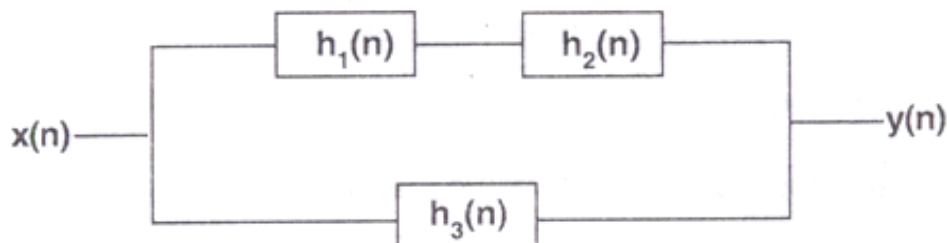
2×10

- (a) Define convolution of two signals. Write the expression for convolution expression of two discrete signals.
- (b) What is causal signal and causal system ?
- (c) Find the circular convolution of the signal
 $X(n) = \{1, -i, 1, -1\}$ and $Y(n) = \{1, 0, 1, i\}$
- (d) What is BIBO stability and write the condition for LTI system ?
- (e) State and derive the time reversal property of z-transform.
- (f) State the interconnection of discrete time system.
- (g) What is twiddle factor ?
- (h) State initial value theorem and final value theorem.
- (i) State complex conjugate property of DFT.
- (j) $y(n) = -n$ is a causal signal or not ? Justify.



P.T.O.

2. (a) Find the inverse z transform of
 $X(z)=1/(1-1.2z^{-1}+0.2z^{-2})$ if ROC : $0.2<|z|<1$ 5
- (b) Explain the realization of LTI system by direct form 1 and direct form 2 with example. 5
3. (a) Determine the impulse response of the system described by the difference equation
 $y(n)=0.6(n-1)-0.08Y(n-2)+x(n)$. 5
- (b) Prove that $r_{yx}(k)=h(-k)*r_{xx}(k)$ where $r_{yx}(k)$ =cross correlation of output and input signal,
 $h(k)$ = impulse response of LTI system and $r_{xx}(k)$ = autocorrelation of input signal. 5
4. (a) Compute the output of the system having impulse response $h(n)=\{1,i+2,-1,0,-1\}$ for the input
 $x(n)=\{1,0,1\}$. 5
- (b) What is normalized cross correlation and what is it's benefit ? 5
5. (a) Determine the z-transform of $\cos(\omega_0 n)u(n)$. 5
- (b) State and prove the differentiation property of Z-transform. 5
6. (a) Calculate the DFT of the discrete sequence $x(n)=\{-1, 2, -1, 1\}$. 5
- (b) State and prove multiplication of two DFT and circular convolution. 5
7. (a) Determine the impulse response of the resultant system. 5



$$h_1(n)=nu(n), h_2(n)=\delta(n-1) \text{ and } h_3(n)=\delta(n-1)$$

- (b) Find the output of the system using DFT IDFT method having impulse response

$h(n) = \{1, 2, 3\}$ for the input $x(n) = \{-1, 1, -1\}$.

5

8. Write short notes on any **two** of the following:

5×2

- (a) One sided Z-transform
- (b) Region of convergence
- (c) Static and Dynamic system
- (d) Properties of DFT.

