Registration No :					

Total Number of Pages: 03

B.Tech PCE6I102

210 6th Semester Regular/Back Examination 2018-19 PROCESS DYNAMICS & CONTROL

BRANCH: CHEM Time: 3 Hours Max Marks: 100 Q.CODE: F219

Answer Question No.1 (Part-1) which is compulsory, any EIGHT from Part-II and any TWO from Part-III.

The figures in the right hand margin indicate marks. The figures in the right hand margin indicate marks. The ordinary, semi-log and log-log graph papers should be provided to the students in the examination hall.

Part- I

Q1 Only Short Answer Type Questions (Answer All-10)

(2 x 10)

- a) What do you mean by inferential control configuration?
- b) Classify the different types of variables in the control system with example.
- c) Differentiate between period of oscillation and natural period of oscillation.
- d) Solve

$$\frac{d^2x}{dt^2} + 3\frac{dx}{dt} + x = 1 \text{ and } x(0) = x'(0) = 0$$

e) Solve the following equation for y(t):

$$\int_{0}^{t} y(\tau)d\tau = \frac{dy(t)}{dt} y(0) = 1$$

- f) A thermometer having a time constant of 0.1 min is at a steady state temperature of 80 °C. At time t=0, the thermometer is placed in a temperature bath maintained at 100°C. Determine the time needed for the thermometer to read 90°C.
- **g)** Draw the block diagram for a process whose output and inputs are related by the following equation:

$$T'(s) = \left[Q(s) + \omega c T'_i(s)\right] \frac{1/\omega c}{\tau s + 1}$$

- h) What do you mean by on-off controller? Give an example.
- i) State the Bode stability criterion in terms of gain margin and phase margin.
- j) Which controller is known as rate controller and why?

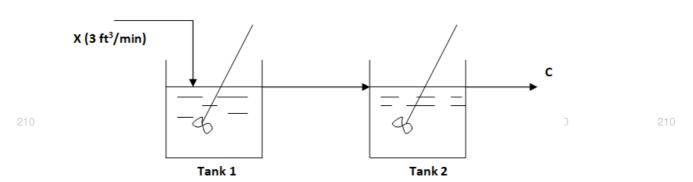
Part-II

Q2 Only Focused-Short Answer Type Questions- (Answer Any Eight out of Twelve)

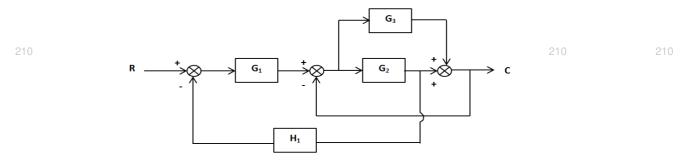
 (6×8)

- a) Discuss about the general needs of a control system.
- **b)** Derive the transfer function of a liquid tank system.
- c) A first order reaction A→B with the rate constant K is taking place in CSTR fed with A at concentration C_{AF} which remains unchanged. There are likely to be some deviations in feed rate (F) of A. Derive the transfer function between concentration of A in the outlet and feed rate of A assuming that volume V of reacting mixture remains unchanged.

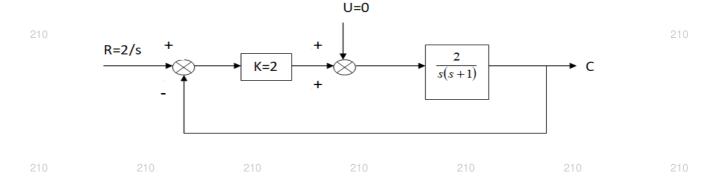
- d) A process of unknown transfer function is subjected to a unit-impulse input. The output of the process is measured accurately and is found to be represented by the function $y(t) = te^{-t}$. Determine the unit step response of this process.
- e) In the two-tank mixing process shown in figure below, x varies from 0 lb salt/ft³ to 1 lb salt/ft³according to a step function. At what time does the salt concentration in tank 2 reach 0.6 lb salt/ft³? The holdup volume of each tank is 6 ft³.



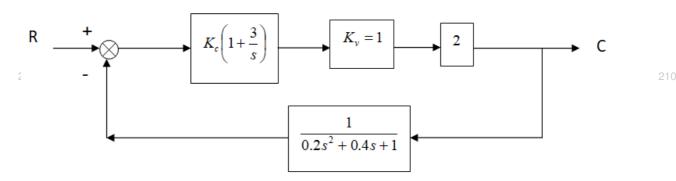
- f) Discuss briefly the hardware of a control system.
- g) What do you mean by proportional band? A pneumatic proportional controller is used to control temperature within the range of 60 to 100 °F. The controller is adlusted so that the output pressure goes from 3 psi (valve fully open) to 15 psi (valve fully closed) as measured temperature goes for 71 to 75 °F with the set point held constant. Find the gain and the proportional band.
- h) Determine the overall transfer function for the following block diagrams.



- i) For the control system given below, determine: 210 210 210
 - $\bullet \quad \frac{C(s)}{R(s)}$
 - Offset
 - $C(\infty)$



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- k) What do you mean by filter? Classify the different types of filter.
- I) Write short notes on:
 - Ratio control
 - Cascade control

Part-III

Only Long Answer Type Questions (Answer Any Two out of Four)

- Q3 a) Prove that the manometer is of a second order system.
 - b) A step change of magnitude 5 is introduced into a system having the transfer function
- (10)

(6) 210

$$\frac{Y(s)}{X(s)} = \frac{10}{s^2 + 2s + 5}$$

Determine:

- Percent overshoot
- Rise time
- Maximum value of Y(t)

 - Ultimate value of Y(t)
 - Peroid of oscillation
- Q4 Sketch the root locus plot for the open loop transfer function given below and determine the (16)stability.

$$G(s)H(s) = \frac{K(s+0.1)}{s(s-0.2)(s^2+s+0.6)}$$
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Q5 Plot the Bode diagram for the control system whose overall transfer function is given by : (16)

$$G(s) = \frac{10(0.2s+1)e^{-s/10}}{(s+1)(0.1s+1)}$$

For the control system of transfer function given by: $(s+1)^3$, determine the controller Q6 (16)setting for a PI controller using C-C method and model the process reaction curve.