Regis	stration No :	
	umber of Pages : 03 210 210 210 210	B.Tec
	6 th Semester Regular Examination 2017-18	PEE6I10
	ELECTRICAL DRIVES BRANCH : ELECTRICAL	
	Time : 3 Hours	
	Max Marks : 100 Q.CODE : C150	
210	Answer Part-A which is compulsory and any four from	
	The figures in the right hand margin indicate mar	KS.
Q1.	<u>Part – A (Answer all the questions)</u> Answer the following questions: <i>multiple type or dash fill up ty</i>	pe: (2 x 10
	An equilibrium point is stable when in speed causes load torg	• • •
b)	the motor torque.	time
210)	In case of Intermittent periodic duty running period is less than constant and rest period is less than time constant.	ume ₂₁₀
c)	For a single phase fully controlled rectifier fed separately excited De	C motor
d)	and quadrant of operation is possible. For a separately excited DC motor under Armature voltage control	maximum
	allowable is constant and under field control maximum allowa	able
e)	For a DC series motor under dynamic braking con	
210 f)	interchanged and for plugging connection is interchanged. Active load torque usually their sign and passive load torc	
•,	their sign when direction of the drive rotation is changed.	
g)	In variable frequency control for above base speed operation	
h)	Pole changing method is applicable to type induction mot power recovery scheme is applicable to type induction motor	•
²¹⁰ i)	VSI fed induction motor drive can be applied to motors an	
j)	induction motor drive is applicable to motors. Coefficient of adhesion with increase in speed and	with
,,	decrease in speed regulation.	
Q2.	Answer the following questions: Short answer type :	(2 x 10
a)	What are the advantages of electrical drive?	
²¹ b)	What are the components of load torque? 210 210 210	210
C)	What is steady state stability for an electric drive?	
d)	What are the requirements of closed loop control of electric drives?	
e)	Why a motor of smaller rating can be selected for a short time duty?	
f) av	What is regenerative braking?	
g)	Differentiate between VSI and CSI fed induction motor drive.	

	210	210 210	210	210	210		210
	h)	What is the difference between static Krame	er drive and static	scherbius drive?			
	i)	What is the difference between true synchrofor a synchronous motor?					
	j)	What is coefficient of adhesion?					
	210	²¹⁰ Part – B (Answer any f	our questions)	210	210		210
Q3.	a)	A motor has heating time constant of 60 min min. Calculate the motor rating for the follow (i) Short-time periodic duty cycle c minutes followed by no load period down.	ving duty cycles: onsisting of 100	kW load for 10	(10)	
	210	 (ii) Intermittent periodic duty consisting and no load period of 10 min. Assume loss to be proportional to (power)². 	210		210		210
	b)	Explain the four quadrant operation of diagrams.		ist with suitable		(5)	
24.	a)	What is load equalisation in an electrical moment of inertia of the flywheel required for			(10)	
	b) ₂₁₀	A motor equipped with a flywheel has to s 10 sec followed by a no load period long en full speed, It is desired to limit the motor to the moment of inertia of the flywheel? The rpm and it has a slip of 8% at torque of 4 torque characteristic to be a straight line in an inertia of 10 kg-m ² .	nough for the flyw orque to 450 N-m. no load speed of 00 N-m. Assume	heel to regain its What should be the motor is 600 the motor speed	210	(5)	210
1 5.	21 a)	 A 220 V, 970 rpm,100A dc separately resistance of 0.05 Ω. It is braked by plugg rpm. Calculate (i) resistance to be placed in armatur twice the full load value (ii) braking torque and (iii) torque when speed has fallen to ze 	ging from an initia re circuit to limit b	al speed of 1000	210 (*	10)	210
	b) 210	Derive the expression for motor speed and excited DC motor with armature control und			210	(5)	210
Q6.	a)	Explain the variable frequency control of an diagram and what is slip speed control?	induction motor d	Irive with suitable	(10)	
	b)	A 2.8 kW 400V, 1370 rpm, 50 Hz, delta motor has the following parameters referred X_r^{\prime} = 5 Ω . The motor speed is controlled by	ed to stator R _s =2 v the stator voltad	Ω , $R_r^{/}$ = 5 Ω X _s =		(5)	
	210	driving a fan load it runs at rated speed terminal voltage, current and torque at 1200	at rated voltage.) rpm.	Calculate motor	210		210
Q7.	a)	What is slip power Recovery scheme? operation with suitable diagram and derive			(10)	
				040			0.1.0

210		b)	A 3-phase 440V, 6 pole, 970 rpm, 50 Hz, Y-connected induction motor has the following parameters referred to stator $R_s=0.2 \Omega$, $R_r'=0.15 \Omega X_s=X_r'=0.4 \Omega$. The stator to rotor turns ratio is 3.5. The motor speed is controlled by the static scherbius drive. The drive is designed for aspeed range of 30% below the synchronous speed. The maximum value of firing angle is 170°. Calculate ₂₁₀ (i) turns ratio of the transformer and (ii) torque for a speed of 750 rpm and α = 140°.	(5)	210
	Q8.	a)	 An electric train weighing 500 tonnes climbs up-gradient with G=8 and following speed-time curve: (i) uniform acceleration of 2.5 km/hr/sec for 60sec (ii) constant speed for 5min 	(10)	
210		210	(ii) coasting for 3 min ²¹⁰		210
		b)	Derive the expression for Tractive Effort and torque per motor for an electric train.	(5)	
210	Q9.	210 a)	Explain the different operation carried out in a textile mill and what are the electrical drives used for these operations?	(10)	210
		b)	Write a short note on Steel Rolling Mill.	(5)	

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