Total Number of Pages: ,02

M .TECH ETPE201

(3)

Second Semester Examination – 2013

RADAR SYSTEM ENGINEERING

Time: 3 Hours

Max marks: 70

Answer Question No.1 which is compulsory and any five from the rest.

The figures in the right hand margin indicate marks.

 (2×10) Answer the following questions: Q1 a) Why Radar frequencies are in microwave range? b) What for a Duplexer unit is used in a Pulse-Radar system? c) What is false alarm and how can it be controlled? A 1 KW pulse radar uses pulses of 1µs duration. What is the p.r.f if the peak power transmitted is 2 MW? e) What is the delay introduced in a delay line canceller of an MTI using a p.r.f 5000 Hz? ---What are glint and echo amplitude fluctuations? What types of tracking are affected by these? g) What should be the spacing between elements of an antenna array of isotropic radiators to avoid grating lobes? h) What is the basic difference between an MTI and a Pulse-Doppler radar? A 4-bit digital phase shifter is used for electronic beam switching. What are the lengths of the switched lines and what is the phase increment in steps? j) What happens to the antenna gain as the beam of a phased array scans through an angle from the broad side? Q2 a) A 1 KW pulse-radar operating at 9 GHz has the following parameters : (7) $= 1 \mu s$ Pulse width (i) = 0.001Duty cycle (ii) Receiver Noise Figure = 10 dB (iii) = 30 dB(iv) Antenna Gain If the indicator minimum requirement is 6 dB SNR, find the maximum range of a target of minimum cross sectional area 10 m².

b) Find the maximum unambiguous range of the above Radar.

Q3	a)	Why can't a CW radar measure range? What modification does a simple CW radar need to measure both range and velocity of targets? What is done to isolate the receiver from the high power transmitter?	(5)
	b)	How is the direction of the moving target (approaching or receding) could be ascertained in a CW radar?	(5)
Q4	a)	What is an MTI? Give the block diagram of the same and explain its operation. Draw the time domain filter characteristics of the delay line canceller.	(6)
	b)	A 3 GHz MTI has a maximum unambiguous range of 150 Km. Find its first and second blind speeds. How can the blind speed range be extended?	(4)
Q5	a)	What are the different types of tracking radars? Explain the basic principle of continuous angle tracking. What are the limitations to tracking	(5)
	b)	Explain the operation of a mono-pulse tracking radar with block diagram. What type of antenna is suitable for this radar?	(5)
Q6	a)	How is the aperture illumination of a line source related to the Electric field intensity as a Fourier Transform pair? Find an expression for the Electric field intensity for a uniform aperture illumination extending from – D/2 to + D/2 in z-axis around the origin. What is the width of the main beam?	(5)
	b)	Explain the terms: (i) Aperture Efficiency (ii) Beam Area (iii) Radiation efficiency in radar antennas.	(5)
Q7	a)	-: I have the received field interests of an M-element	(6)
The second secon	<u>b)</u>	the section of through an angle A from the	(4)
Q3	a) b) c) d)	Write brief explanatory notes on any two of the followings: Synthetic Aperture Radar Cassegrain Antenna Diode Phase Shifters AMTI	(5 x 2)