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2nd Semester Regular Examination 2016-17 Statistical Signal Processing BRANCH: COMMUNICATION ENGG, COMMUNICATION SYSTEMS, ELECTRO & COMM. ENGG, ELECTRO AND TELECOMMUNICATION ENGG, SIGNAL PROCESSING Time: 3 Hours Max Marks: 100 Q.CODE: 2849

Answer Question No.1 which is compulsory and any FOUR from the rest. The figures in the right hand margin indicate marks.

Q1 Answer the following questions: **Short answer type**

(2 x 10)

- a) Evaluate the z-transform of a function x(n) when it passes through a D-flip flop operating at 2 MHz clock frequency.
- **b)** Evaluate and sketch the RoC of a function given as $\alpha^n u(n)$.
- c) Which has better convergence: LMS or RLS algorithm? Justify.
- **d)** Does the function y(n) = kx(n) + C, where k, C are constants and x(n) is a fixed phase sinusoid, represent a random process? Justify.
- e) The autocorrelation function of a function x(n) is an ensemble average or a time average? Explain clearly.
- f) What is stationary in a stationary random process? Explain.
- **g)** How many poles and zeros characterize an AR process given as *AR*(3) ?
- h) What are the sizes of the autocorrelation function and the crosscorrelation function for an FIR Wiener filter that has five no.s of taps?.
- i) Write down two salient features of a rectangular window.
- j) Give the frequency response of a filter of length N having an impulse

response given as
$$h(n) = \begin{cases} \frac{1}{N} \exp(jn\omega_i); & 0 \le n < N \\ 0 & \text{otherwise} \end{cases}$$

What is a reconstruction filter? Give its impulse response.

Q2 a) Find the autocorrelation sequence of a function whose PSD is given as (10) $(2z^{2}+5z-2)$

$$P_x(z) = \frac{-2z + 3z - 2}{3z^2 + 10z + 3}$$

b) Determine if the following two functions are valid autocorrelation (10) sequences: (i) $r_x(k) = 3\delta(k) + 2\delta(k-1) + 2\delta(k+1)$ and (ii) $r_x(k) = \exp(jk\pi/4)$.

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- **Q3 a)** How can you make the function given as $e^{-\frac{(x-a)^2}{2\sigma^2}}$ a probability distribution function? Compute its mean and the standard deviation (10)
 - **b)** Find and sketch the PSD for the following autocorrelation functions (10)

(i)
$$r_x(k) = \delta(k) + 2(0.5)^{|k|}$$
 (ii) $r_x(k) = 2\delta(k) + \cos\left(\frac{\pi k}{4}\right)^{k}$

Write comments on the results so obtained.

Q4 a) The input to an LTI system with impulse response (10) $h(n) = \delta(n) + \frac{1}{2}\delta(n-1) + \frac{1}{4}\delta(n-2)$ is a zero mean WSS process with autocorrelation given as $r_x(k) = \left(\frac{1}{2}\right)^{|k|}$. Find out the variance and the autocorrelation of the output process.

b) Unit variance white noise is applied to a filter having an impulse (10) response given as $h(n) = \frac{2}{3} \left(-\frac{1}{3}\right)^n u(n) + \frac{1}{3} \left(-\frac{1}{3}\right)^{n-2} u(n-2)$. Find the PSD of the resulting output. Sketch the PSD.

Show that a sufficient condition for a WSS process to be ergodic in the mean is that the autocovariance is absolutely summable, i.e.

$$\sum_{k=-\infty}^{\infty} \left| c_x(k) \right| < \infty$$

- **Q5 a)** Is the autocorrelation matrix of a random phase sinusoid positive (10) definite? Examine first by finding the matrix.
 - **b)** Establish the relationship between the power spectrum and the (10) ensemble average of the Fourier magnitude of a given function x(n).
- **Q6 a)** Design the optimum linear predictor for a real-valued AR(2) process (10) defined as x(n) = 0.9x(n-1) 0.2x(n-2) + w(n) where w(n) is unit variance zero mean white noise.
 - **b)** A noisy signal is expressed as y(n) = x(n) + 0.6x(n-1) + w(n) where w(n) (10) is a zero mean random white noise with unit variance. The signal x(n) is a WSS AR(1) process with autocorrelation values given as $[4, 2, 1, 0.5]^T$. Design a non causal IIR Wiener filter that produces the MMSE of x(n).
- **Q7 a)** Evaluate the power spectrum of a random phase sinusoid embedded in a random white noise with unity variance. The phase is uniformly distributed in the interval of $[-\pi,\pi]$. Hence find out the mean value of the periodogram of this signal.
 - b) Show that the LMS algorithm implements a low pass filter. Find out its convergence conditions. Hence, establish a relationship between the filter and the rate of convergence.